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## ON OSCILLATORY PROPERTIES OF SECOND ORDER SYSTEMS OF ORDINARY DIFFERENTIAL EQUATIONS

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Consider the system

$$u' = p(t)v,$$
  

$$v' = -q(t)u,$$
(1)

where  $p,q:[0,+\infty[ \rightarrow [0,+\infty[$  are locally summable functions.

**Definition.** The system (1) is said to be oscillatory if it has at least one oscillatory solution and nonoscillatory otherwise.

It is known (see [1]) that if

$$\int_{0}^{+\infty} p(s) \, ds = +\infty \quad \text{and} \quad \int_{0}^{+\infty} q(s) \, ds = +\infty,$$

then the system (1) is oscillatory, but if

$$\int_{-\infty}^{+\infty} p(s) \, ds < +\infty \quad \text{and} \quad \int_{-\infty}^{+\infty} q(s) \, ds < +\infty,$$

then it is nonoscillatory.

Therefore we will assume that

$$\int_{-\infty}^{+\infty} p(s) \, ds = +\infty \quad \text{and} \quad \int_{-\infty}^{+\infty} q(s) \, ds < +\infty.$$
(2)

(The case where  $\int_{-\infty}^{+\infty} p(s) ds < +\infty$  and  $\int_{-\infty}^{+\infty} q(s) ds = +\infty$  can be easily reduced to the case (2)).

As shown in [2], if the condition (2) is fulfilled and for some  $\lambda < 1$ 

$$\int^{+\infty} f^{\lambda}(s)q(s) \, ds = +\infty,$$

where

$$f(t) = \int_{0}^{t} p(s) \, ds, \qquad (3)$$

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then the system (1) is oscillatory.

Therefore we will consider the case where

$$\int^{+\infty} p(s) \, ds = +\infty \quad \text{and} \quad \int^{+\infty} f^{\lambda}(s) q(s) \, ds < +\infty \quad \text{for all } \lambda < 1,$$

where f is the function defined by (3). Introduce the notation

$$g_*(\lambda) = \liminf_{t \to +\infty} f^{1-\lambda}(t) \int_t^{+\infty} f^{\lambda}(s)q(s) \, ds,$$
$$g^*(\lambda) = \limsup_{t \to +\infty} f^{1-\lambda}(t) \int_t^{+\infty} f^{\lambda}(s)q(s) \, ds$$

for  $\lambda < 1$  and

$$g_*(\lambda) = \liminf_{t \to +\infty} f^{1-\lambda}(t) \int_0^t f^{\lambda}(s)q(s) \, ds,$$
$$g^*(\lambda) = \limsup_{t \to +\infty} f^{1-\lambda}(t) \int_0^t f^{\lambda}(s)q(s) \, ds$$

for  $\lambda > 1$ .

**Theorem 1.** Let  $g_*(0) \le \frac{1}{4}$ ,  $g_*(2) \le \frac{1}{4}$  and

$$g^{*}(0) > g_{*}(0) + \frac{1}{2} \left( \sqrt{1 - 4g_{*}(0)} + \sqrt{1 - 4g_{*}(2)} \right).$$

Then the system (1) is oscillatory.

**Theorem 2.** Let  $g_*(0) \leq \frac{1}{4}$  and  $g_*(2) \leq \frac{1}{4}$ . Moreover, let either

$$g^*(\lambda) > \frac{\lambda^2}{4(1-\lambda)} + \frac{1}{2} \left(1 + \sqrt{1 - 4g_*(2)}\right)$$

for some  $\lambda < 1$  or

$$g^*(\lambda) > \frac{\lambda^2}{4(\lambda-1)} - \frac{1}{2} \left(1 - \sqrt{1 - 4g_*(0)}\right)$$

for some  $\lambda > 1$ . Then the system (1) is oscillatory.

Corollary 1. Let

$$\lim_{\lambda \to 1} |1 - \lambda| g^*(\lambda) > \frac{1}{4}.$$

Then the system (1) is oscillatory.

**Corollary 2.** Let for some  $\lambda \neq 1$ 

$$|1-\lambda|g_*(\lambda)>\frac{1}{4}.$$

Then the system (1) is oscillatory.

**Theorem 3.** If for some  $\lambda \neq 1$ 

$$|1-\lambda|g_*(\lambda) > \frac{(2\lambda-1)(3-2\lambda)}{4}, \quad |1-\lambda|g^*(\lambda) < \frac{1}{4}.$$

then the system (1) is nonoscillatory.

## References

1. J. D. Mirzov, Asymptotic behaviour of solutions of systems of nonlinear nonautonomous ordinary differential equations. (Russian) *Maikop*, 1993.

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